

# Compressed Sensing using Generative Models

**Ashish Bora**   Ajil Jalal   Eric Price   Alex Dimakis

UT Austin

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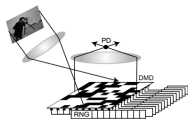
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Medical  
Imaging



Astronomy



Single-Pixel  
Camera



Oil Exploration

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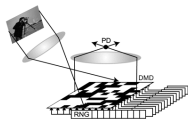
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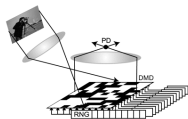
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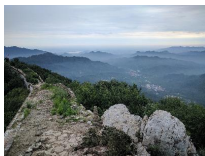


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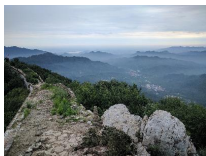
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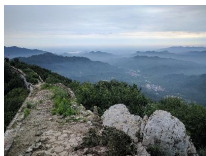
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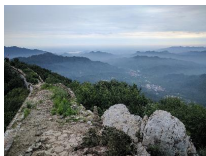
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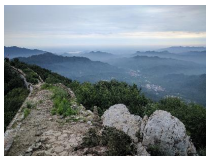


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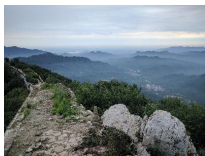


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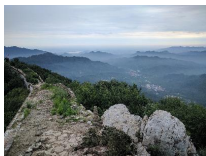


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  - ▶ Measurements “incoherent”  $\implies$  most info new.



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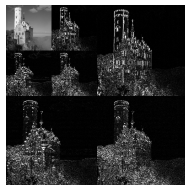
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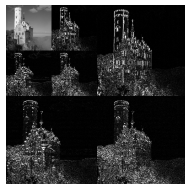
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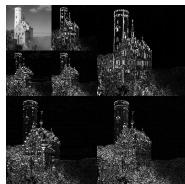
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  - ▶ In particular: *generative models*.

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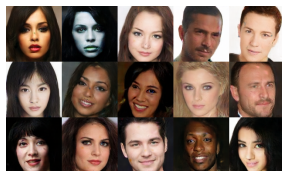
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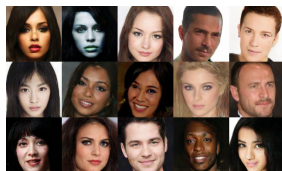
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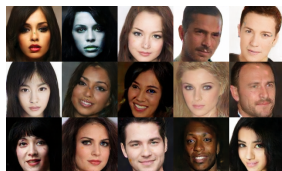
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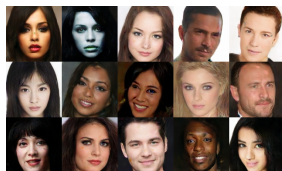
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  - ▶ Blurrier, but maybe better coverage of the space.

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- Variational Auto-Encoders (VAEs) [Kingma & Welling 2013].
  - ▶ Blurrier, but maybe better coverage of the space.

Suggestion for compressed sensing

Replace “ $x$  is  $k$ -sparse” by “ $x$  is in range of  $G : \mathbb{R}^k \rightarrow \mathbb{R}^n$ ”.

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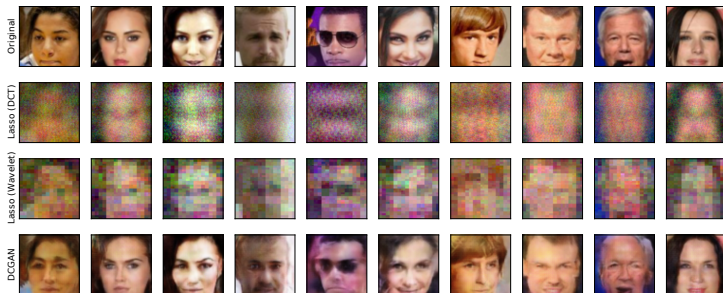
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  - ▶ In practice, optimization error is negligible.

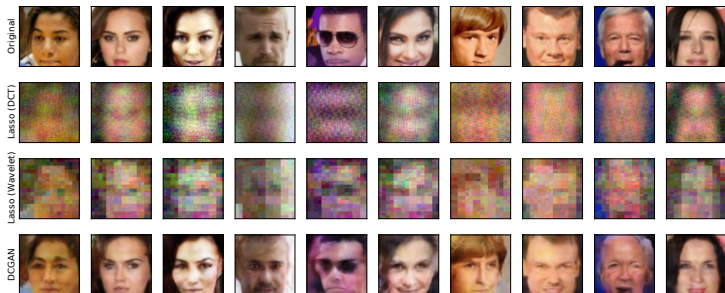
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Faces:  $n = 64 \times 64 \times 3 = 12288$ ,  $m = 500$

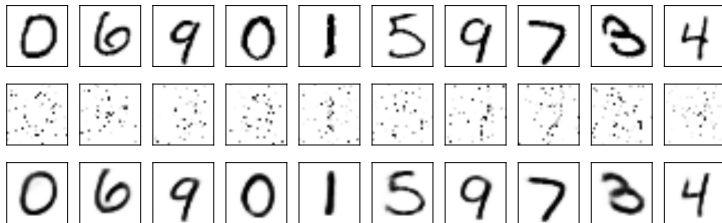


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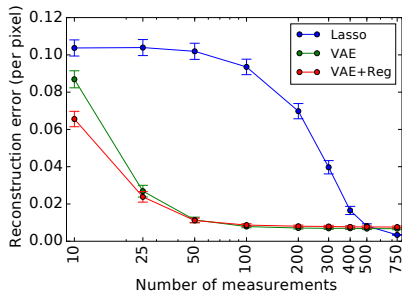


MNIST:  $n = 28 \times 28 = 784$ ,  $m = 100$ .

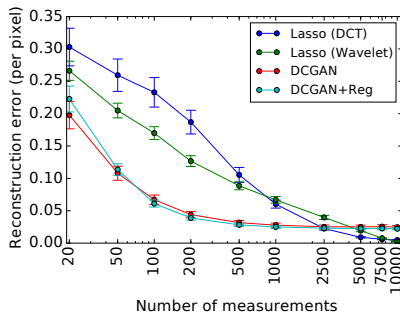


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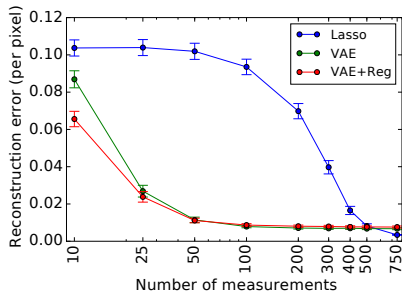


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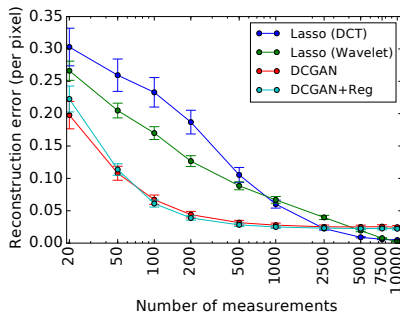


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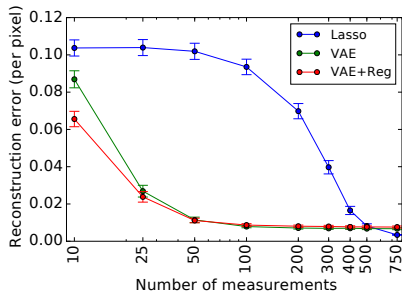
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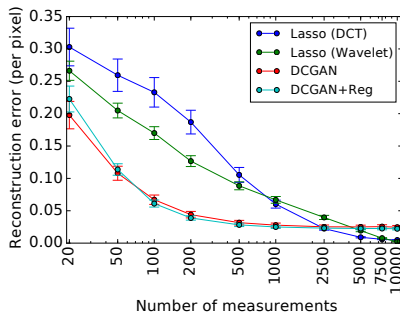
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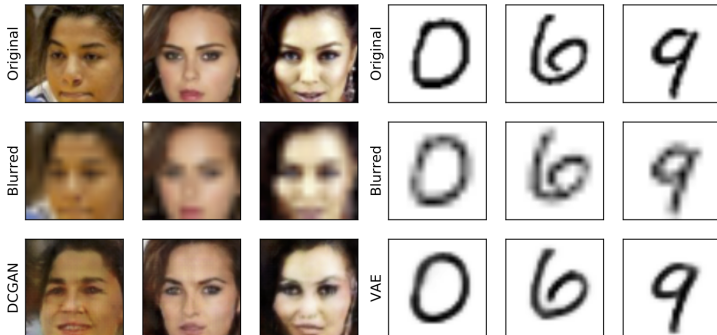
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  - ▶ Guarantee only holds if  $G$  and  $A$  are “incoherent”.

# Inpainting



# Super-resolution





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