Edge Conductance Estimation using MCMC

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Outline



• What is conductance?

• Why estimate conductances?

2 Notation

3 Prior Work

4 Algorithm

- Motivation
- Idea
- Pseudocode

5 Theoretical results

6 Simulation Experiments

- Cardinal Estimation
- Ordinal Estimation

Discussion

Outline

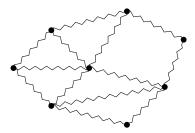


What is conductance?

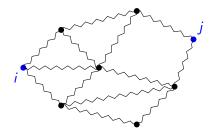
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• Given a graph G = (V, E), imagine each edge as a unit resistor.

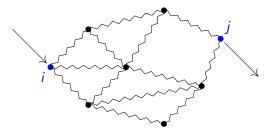


Definition



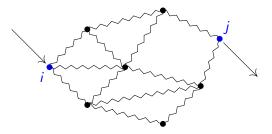
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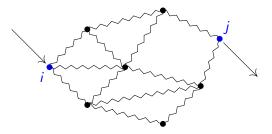
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- Inject unit current at *i* and extract it at *j*.
- Effective resistance between *i* and *j* is the potential difference between them.
- Effective conductance is inverse of effective resistance.

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- Edge resistances for graph sparsification [3]
 - Edges sampled (with replacement) according to their effective resistance
 - Approximately preseves quadratic form of Graph Laplacian (i.e. $x^{\top}Lx$)

- G = (V, E) is an undirected, unweighted, connected, finite graph.
 m = |E|, n = |V|
- $\partial_i = \{j \mid (i,j) \in E\}$
- $d_i = |\partial_i|$
- $d_{max} = \max_{i \in V} d_i$, $d_{min} = \min_{i \in V} d_i$
- $d_{ij} = \min\{di, dj\}, D_{ij} = \max\{d_i, d_j\}.$
- $\pi_i = d_i/2m$, stationary distribution of simple random walk on G
- $d_{avg} = \sum_{i \in V} d_i \pi_i$
- G_{ij} = the effective conductance between i and j
- R_{ij} = the effective resistance between *i* and *j*

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- [3] uses low dimensional random projection to preserve pairwise distances to estimate resistances. Takes only $\widetilde{O}(m/\epsilon^2)$ steps, but requires centralized computation.

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- Are incremental and adaptive

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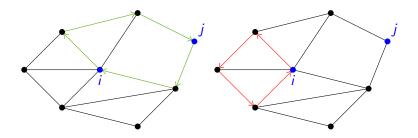
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- A random walk on the graph picks, from the current position, one of the neighbors with equal probability. Such random walks naturally give us many of the desired properties.
- We assume positive recurrence of the associated Markov Chain.

• Let p_{ij} denote the probability that a random walk starting at node *i* visits node *j* before returning to node *i*.



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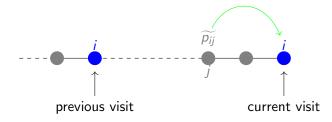
- We estimate this probability by averaging results from several *i* to *i* paths in a random walk.
- We will show how this can be done only with local communication for edge conductance estimation.

• \tilde{p}_{ij} is boolean. It denotes the the success or failure of visiting node j in an instance of a return path from node i to node i of the random walk.

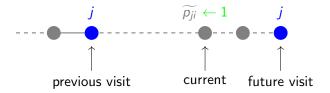
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- N_i is the number of times node i was visited.
- \hat{p}_{ij} is a running estimate of p_{ij} .

 In the long run, every visit to node *i* marks the end of a return path. Thus, on visiting node *i*, we can update p̂_{ij} using p̂_{ij}.



A visit to node *i* at time *t* will be a part of a cycle that originated at node *j* prior to time *t* and a subsequent return to node *j* after time *t* (with probability 1, because of positive recurrence). Thus a visit to node *i* can be used to update p_i.



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Algorithm 1 Visit Before Return **Require:** T, G = (V, E)1: $\forall i \in V, N_i \leftarrow 0$ 2: \forall $(i, j) \in E, \widehat{p}_{ii} = \widetilde{p}_{ii} = 0.$ 3: Sample initial node X_1 from the stationary distribution π . 4: for $t = [1, 2, 3, \dots, T]$ do Let $i = X_t$ 5: **for all** *j* in ∂_i **do** 6: $\widehat{p}_{ii} \leftarrow (\widehat{p}_{ii}N_i + \widetilde{p}_{ii})/(N_i + 1)$ 7: $\widetilde{p}_{ii} \leftarrow 0$ 8. $\widetilde{p}_{ii} \leftarrow 1$ 9: $N_i \leftarrow N_i + 1$ 10. 11: Jump to a neighbor of the current node as identified by the walk. 12: For every $(i,j) \in E$, output $\widehat{G}_{ij} = \max\left(1, \frac{d_i}{2}\widehat{p}_{ij} + \frac{d_j}{2}\widehat{p}_{ji}\right)$.

Theorem (Performance of VisitBeforeReturn)

Fix an edge $(i,j) \in E$. For any $0 < \epsilon < d_{ij}^2/(4m)$ and $0 < \delta < 1/2$,

$$T = \widetilde{O}\left(D_{ij}\cdot \max\{m, D_{ij}t_{mix}\}\cdot rac{1}{\epsilon^2}\lograc{1}{\delta}
ight)$$

steps suffice to ensure that the output \widehat{G}_{ij} of the algorithm **VisitBeforeReturn** satisfies

$$\mathbb{P}(|\widehat{G}_{ij} - G_{ij}| \ge \epsilon) \le \delta.$$

If the algorithm is run for T steps, it requires $O(d_{avg}T)$ computation steps on the average (worst case $O(d_{max}T)$ computations), and uses $O(m \log T)$ space. •

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- Combine the two.

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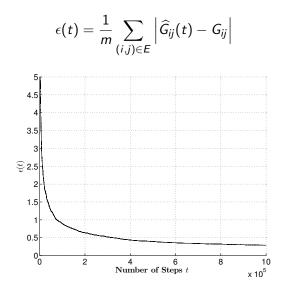
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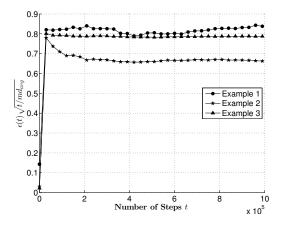


Ashish Bora, Vivek S. Borkar , Dinesh Garg, Rajesh Sundaresan Edge Conductance

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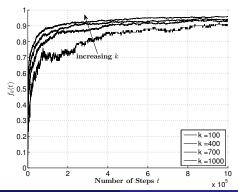
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Simulation Experiments

Top-k set estimation

- Incremental approximate estimation algorithms can typically recover ordering much faster than exact values.
- We test performance of our algorithm for recovering top-*k* edges with high conductance by plotting fraction of top-*k* largest conductance edges correctly identified at time *t*.



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- We have presented a MCMC based scheme to approximate edge conductances.
- Our algorithm is incremental and iterative, can be easily distributed, works with local communication, and uses very little memory and computation per step.
- We provide theoretical guarantees on the performance.
- Simulation experiments support our theoretical results.

References

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Thank you for your attention! Questions?

• Estimating resistances from conductances

$$\begin{split} \mathbb{P}\left(\frac{|\widehat{R}_{ij} - R_{ij}|}{R_{ij}} \ge \epsilon\right) &= \mathbb{P}\left(\left|\frac{\widehat{R}_{ij}}{R_{ij}} - 1\right| \ge \epsilon\right) \\ &= \mathbb{P}\left(\left|\frac{G_{ij}}{\widehat{G}_{ij}} - 1\right| \ge \epsilon\right) \\ &= \mathbb{P}(|G_{ij} - \widehat{G}_{ij}| \ge \epsilon \widehat{G}_{ij}) \\ &\leq \mathbb{P}(|\widehat{G}_{ij} - G_{ij}| \ge \epsilon), \end{split}$$

where the last inequality follows because $\widehat{G}_{ij} \geq 1$.

- Our algorithm can be easily adapted for estimating the conductance value across any pair of nodes: maintain and update the variable $\widehat{p_{ij}}$ and $\widetilde{p_{ij}}$.
- If effective conductances between far-off nodes is desired, the communication is however no longer local.